

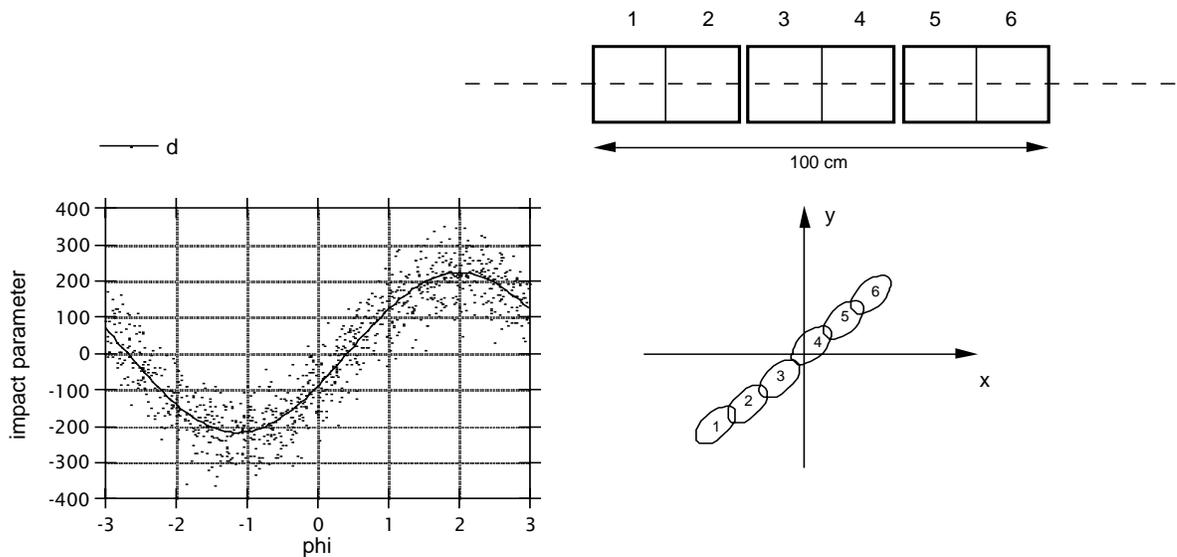
BEAM ALIGNMENT ISSUES

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- **Detector alignment**
 - We assume that with a combined on-line and off-line analysis we can come up with a set of constants for SVT to compute constraints and track parameters within some 3D coordinate system: the "SVT coordinate system".
 - We do not need to change these constants unless the detector (SVT+COT) moves in some non-rigid way.
 - In principle these constants are NOT dependent on the position of the beam spot.
- **Beam alignment**
 - The goal of the beam alignment procedure is to always keep the beam spot of the Tevatron as close as possible to the "nominal beam position".
- **Nominal beam position**
 - This is where we want the beam spot to be during data taking.
 - Defined with respect to the SVT coordinate system
 - Position: (x, y) and slope (dx, dy)

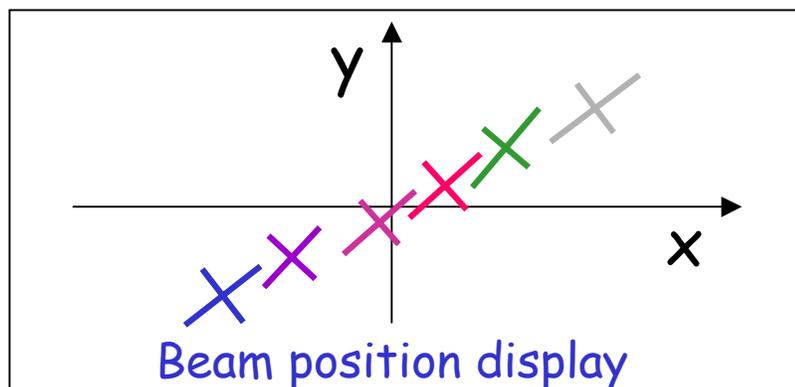
MEASURING 3D BEAM POSITION

- **Semi-offline**
 - Impact parameter and phi from SVT
 - z from offline tracks
- **Online**
 - Impact parameter and phi from SVT
 - Rough z from SVT segmentation



MEASURING 3D BEAM POSITION (online)

- Read BP_FIFO's of all Track Fitters
 - 32K tracks per phi sector
- Select "high quality" tracks contained in a single z segment
- Use (d, ϕ)
 - ϕ : phi angle at min distance from origin
- For each z segment accumulate quantities needed for the fit
 - $\sum d_i \cdot \cos \phi_i, \sum d_i \cdot \sin \phi_i, \sum \cos^2 \phi_i, \sum \sin^2 \phi_i \dots$ etc.
- For each value of z:
 - Solve 2x2 linear system to find beam center
 - (X_k, Y_k) : $k = 1 \dots 6$
 - Perform a 3 parameter linear fit to find beam shape
 - $(\sigma_x, \sigma_y, \sigma_{xy})$: $k = 1 \dots 6$
- Beam spot parameters are obtained fitting $X(z), Y(z)$



DEFINING NOMINAL BEAM POSITION

- Find range of beam position control
 - Xmin, Xmax, Ymin, Ymax
 - DXmin, DXmax, DYmin, DYmax
- Define: nominal = (min + max)/2
- Physically move the detector until:
 - DXnom ~ 0
 - DYnom ~ 0may require iteration of detector alignment
- Shift SVT coordinate system to
 - Xnom = 0
 - Ynom = 0requires adjustment of fitting constants
- Define nominal beam position as
 - X = 0; Y = 0; DX = 0; DY = 0;

- Accelerator coordinate system vs. SVT coordinate system
 - calibration?